DESCRIPTION
The MPQ3426 is a current-mode step-up converter with a 6A, 90mΩ internal switch that provides a highly efficient regulator with a fast response. The MPQ3426 features a programmable frequency of up to 2MHz that allows for easy filtering and reduces noise. An external compensation pin gives the user flexibility in setting loop dynamics, and uses small, low-ESR, ceramic output capacitors. Soft-start results in a small inrush current and can be programmed with an external capacitor. The MPQ3426 operates from an input voltage as low as 3.2V and can generate up to a 35V output.

The MPQ3426's features include under-voltage lockout, current limiting, and thermal overload protection. The MPQ3426 is available in a low-profile 14-pin 3mm×4mm QFN package with an exposed pad.

FEATURES
- Guaranteed Industrial/Automotive Temp. Range Limits
- 6A, 90mΩ, 45V Power MOSFET
- Uses Very Small Capacitors and Inductors
- Wide Input Range: 3.2V to 22V
- Output Voltage as High as 35V
- Programmable fsw: 300kHz to 2MHz
- Programmable UVLO, Soft-Start, UVLO Hysteresis
- Micropower Shutdown <1μA
- Thermal Shutdown 160°C
- Available in 14-Pin 3mm×4mm QFN Package
- Available in AEC-Q100 Qualified Grade

APPLICATIONS
- Telecom—Power Supplies
- Audio—Microphone and Tuner Bias
- Automotive

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ORDERING INFORMATION

<table>
<thead>
<tr>
<th>Part Number</th>
<th>Package</th>
<th>Top Marking</th>
</tr>
</thead>
<tbody>
<tr>
<td>MPQ3426DL*</td>
<td>QFN-14 (3mmx4mm)</td>
<td>See Below</td>
</tr>
<tr>
<td>MPQ3426DL-AEC1**</td>
<td>QFN-14 (3mmx4mm)</td>
<td>See Below</td>
</tr>
<tr>
<td>MPQ3426DLE-AEC1***</td>
<td>QFN-14 (3mmx4mm)</td>
<td>See Below</td>
</tr>
</tbody>
</table>

* For Tape & Reel, add suffix -Z (e.g. MPQ3426DL-Z).
For RoHS Compliant Packaging, add suffix -LF (e.g. MPQ3426DL-LF-Z)
** For Tape & Reel, add suffix -Z (e.g. MPQ3426DL-AEC1-Z).
For RoHS Compliant Packaging, add suffix -LF (e.g. MPQ3426DL-AEC1-LF-Z)
*** For Tape & Reel, add suffix -Z (e.g. MPQ3426DLE-AEC1-Z).
For RoHS Compliant Packaging, add suffix -LF (e.g. MPQ3426DLE-AEC1-LF-Z)

TOP MARKING

MPYW
3426
LLL

MP: MPS prefix:
Y: year code;
W: week code:
3426: first four digits of the part number;
LLL: lot number;

PACKAGE REFERENCE

TOP VIEW

QFN-14 (3mmx4mm)
**ABSOLUTE MAXIMUM RATINGS**

<table>
<thead>
<tr>
<th>Rating</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>SW</td>
<td>-0.5V to +45V</td>
</tr>
<tr>
<td>IN</td>
<td>-0.5V to +24V</td>
</tr>
<tr>
<td>All Other Pins</td>
<td>-0.3V to +6.5V</td>
</tr>
</tbody>
</table>

**Continuous Power Dissipation**

QFN-14 (3mmX4mm) ................................ 2.5W

**Junction Temperature**

150°C

**Lead Temperature**

260°C

**Storage Temperature**

-65°C to +150°C

**Recommended Operating Conditions**

Supply Voltage $V_{IN}$ .................. 3.2V to 22V

Output Voltage $V_{OUT}$ ................. 3.2V to 35V

Operating Junction Temp ($T_J$) ........ -40°C to +125°C

**Thermal Resistance**

<table>
<thead>
<tr>
<th>Package</th>
<th>$\theta_{JA}$</th>
<th>$\theta_{JC}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>QFN-14 (3mmX4mm)</td>
<td>50</td>
<td>12°C/W</td>
</tr>
</tbody>
</table>

**Notes:**

1) Absolute maximum are rated under room temperature unless otherwise noted. Exceeding these ratings may damage the device.

2) The maximum allowable power dissipation is a function of the maximum junction temperature $T_J(\text{MAX})$, the junction-to-ambient thermal resistance $\theta_{JA}$, and the ambient temperature $T_A$. The maximum allowable continuous power dissipation at any ambient temperature is calculated by $P_{D(\text{MAX})}=(T_J(\text{MAX})-T_A)/\theta_{JA}$. Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.

3) The device is not guaranteed to function outside of its operating conditions.

4) Measured on JESD51-7, 4-layer PCB.
### ELECTRICAL CHARACTERISTICS

$V_{IN} = V_{EN} = 5V$, $T_J = -40^\circ C$ to $+125^\circ C$ Typical values are at $T_J = +25^\circ C$, unless otherwise noted.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Input Voltage</td>
<td>$V_{IN}$</td>
<td></td>
<td>3.2</td>
<td>22</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Under-Voltage Lockout</td>
<td>$V_{IN}$ Rising</td>
<td>$T_J=25^\circ C$</td>
<td>2.8</td>
<td>3.1</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Under-Voltage Lockout Hysteresis</td>
<td></td>
<td></td>
<td></td>
<td>2.75</td>
<td>3.15</td>
<td>mV</td>
</tr>
<tr>
<td>VDD Voltage Gate Drive Voltage Supply</td>
<td>$V_{VDD}$</td>
<td>$C = 10nF$</td>
<td>4.6</td>
<td>5.9</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Supply Current (Shutdown)</td>
<td>$V_{EN}$ = 0V</td>
<td></td>
<td>1</td>
<td></td>
<td></td>
<td>μA</td>
</tr>
<tr>
<td>Supply Current (Quiescent)</td>
<td>$V_{FB} = 1.35V$</td>
<td>$T_J=25^\circ C$</td>
<td>650</td>
<td>900</td>
<td>950</td>
<td>μA</td>
</tr>
<tr>
<td>Switching Frequency</td>
<td>$R_{FSET} = 84.5k\Omega$</td>
<td></td>
<td>450</td>
<td>540</td>
<td>630</td>
<td>kHz</td>
</tr>
<tr>
<td>Minimum OFF Time</td>
<td>$V_{FB} = 0V$</td>
<td></td>
<td>80</td>
<td>150</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>Minimum ON Time</td>
<td>$V_{FB} = 1.35V$</td>
<td></td>
<td>100</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>EN Turn-On Threshold</td>
<td>$V_{EN}$ Rising</td>
<td>$T_J=25^\circ C$</td>
<td>1.45</td>
<td>1.5</td>
<td>1.55</td>
<td>V</td>
</tr>
<tr>
<td>EN High Threshold (Micro power)</td>
<td>$V_{EN}$ Rising</td>
<td></td>
<td>1.4</td>
<td>1.0</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>EN Low Threshold (Micro power)</td>
<td>$V_{EN}$ Falling</td>
<td>$T_J=25^\circ C$</td>
<td>0.5</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>EN Input Bias Current</td>
<td>$V_{EN} = 0V, 5V$</td>
<td></td>
<td>0.1</td>
<td>1</td>
<td></td>
<td>μA</td>
</tr>
<tr>
<td>UVLO Hysteresis Current to EN</td>
<td>$1.0 &lt; EN &lt; 1.4$</td>
<td></td>
<td>4</td>
<td></td>
<td></td>
<td>μA</td>
</tr>
<tr>
<td>Soft-Start Current</td>
<td></td>
<td></td>
<td>4</td>
<td>6</td>
<td>8</td>
<td>μA</td>
</tr>
<tr>
<td>FB Voltage</td>
<td></td>
<td>$T_J=25^\circ C$</td>
<td>1.200</td>
<td>1.225</td>
<td>1.250</td>
<td>V</td>
</tr>
<tr>
<td>FB Input Bias Current</td>
<td></td>
<td></td>
<td>1.19</td>
<td>1.19</td>
<td>1.26</td>
<td>nA</td>
</tr>
<tr>
<td>Error Amp. Voltage Gain</td>
<td>$A_{VEA}$</td>
<td></td>
<td>300</td>
<td></td>
<td></td>
<td>V/V</td>
</tr>
<tr>
<td>Error Amp. Transconductance</td>
<td>$G_{EA}$</td>
<td></td>
<td>160</td>
<td></td>
<td></td>
<td>μA/V</td>
</tr>
<tr>
<td>Error Amp. Output Current</td>
<td></td>
<td></td>
<td>15</td>
<td></td>
<td></td>
<td>μA</td>
</tr>
<tr>
<td>GCS : $I_{SW}/V_{COMP}$</td>
<td>$G_{CS}$</td>
<td></td>
<td>18</td>
<td></td>
<td></td>
<td>A/V</td>
</tr>
<tr>
<td>SW ON Resistance</td>
<td>$R_{ON}$</td>
<td>$I_{SW} = 100mA$</td>
<td></td>
<td>90</td>
<td></td>
<td>mΩ</td>
</tr>
<tr>
<td>SW Current Limit</td>
<td></td>
<td>Duty Cycle = 0%</td>
<td>$T_J=25^\circ C$</td>
<td>6.8</td>
<td>6.2</td>
<td>8.5</td>
</tr>
<tr>
<td>Thermal Shutdown</td>
<td></td>
<td></td>
<td>160</td>
<td></td>
<td></td>
<td>°C</td>
</tr>
</tbody>
</table>

**Notes:**

5) Guaranteed by design, not tested.

6) Refer to the “APPLICATION INFORMATION-EN UVLO Hysteresis”.
TYPICAL PERFORMANCE CHARACTERISTICS

$V_{IN}=12V$, $V_{OUT}=24V$, $L=15\mu H$, $C_{OUT}=4.7\mu F \times 2$, $f_{SW}=300kHz$, $T_A=+25^\circ C$, unless otherwise noted.
TYPICAL PERFORMANCE CHARACTERISTICS (continued)

V<sub>FB</sub> Voltage vs. T<sub>A</sub>  
I<sub>Q</sub> Current vs. T<sub>A</sub>  
Current Limit vs. T<sub>A</sub>

Enable Voltage vs. T<sub>A</sub>  
V<sub>IN</sub> UVLO Voltage vs. T<sub>A</sub>  
F<sub>SW</sub> Frequency vs. T<sub>A</sub>

V<sub>DD</sub> Regulation vs. T<sub>A</sub>  
V<sub>DD</sub> UVLO Voltage vs. T<sub>A</sub>  
F<sub>SET</sub> Voltage vs. T<sub>A</sub>
TYPICAL PERFORMANCE CHARACTERISTICS (continued)

$V_{IN} = 12V$, $V_{OUT} = 24V$, $L = 15\mu H$, $C_{OUT} = 4.7\mu F \times 2$, $f_{SW} = 300kHz$, $T_A = +25^\circ C$, unless otherwise noted.

**VOUT Ripple**

$I_{OUT} = 1A$

**Load Transient Response**

$I_{OUT} = 0\to 0.5A$, $0.1\mu s$

$I_{OUT} = 0.5A\to 1A$, $0.1\mu s$

---

**EN Startup**

$I_{OUT} = 0A$

**EN Shutdown**

$I_{OUT} = 0A$

**VIN Startup**

$I_{OUT} = 0A$

---

**VIN Startup**

$I_{OUT} = 0A$

---

**VIN Startup**

$I_{OUT} = 1A$
TYPICAL PERFORMANCE CHARACTERISTICS (continued)

$V_{\text{IN}}=12\text{V}, \ V_{\text{OUT}}=24\text{V}, \ L=15\mu\text{H}, \ C_{\text{OUT}}=4.7\mu\text{F}\times2, \ f_{\text{SW}}=300\text{kHz}, \ T_A=+25^\circ\text{C}, \text{ unless otherwise noted.}$

**VIN SHUTDOWN**

$I_{\text{OUT}}=0\text{A}$

**VIN SHUTDOWN**

$I_{\text{OUT}}=1\text{A}$

---

**Figures**: 
- Voltage and current waveforms under various conditions.
- Labels include: $V_{\text{OUT}}$, $V_{\text{IN}}$, $V_{\text{SW}}$, $I_L$, with corresponding divisions for voltage and current scales.
- Time scales: 400ms/div. for the left figure; 2ms/div. for the right figure.
## PIN FUNCTIONS

<table>
<thead>
<tr>
<th>QFN14 Pin #</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>COMP</td>
<td>Compensation. Connect a capacitor and resistor in series to Analog ground for loop stability.</td>
</tr>
<tr>
<td>2</td>
<td>EN</td>
<td>Regulator On/Off Control Input. A high input at EN turns on the converter, and a low input turns it off. When not used, connect EN to the input source (through a 100kΩ pull-up resistor if V_IN &gt; 6V) for automatic startup. EN pin can also be used to program VIN UVLO. Do not leave EN floating.</td>
</tr>
<tr>
<td>3</td>
<td>VIN</td>
<td>Input Supply. VIN must be locally bypassed.</td>
</tr>
<tr>
<td>4, 5, 6</td>
<td>SW</td>
<td>Power Switch Output. SW is the drain of the internal MOSFET switch. Connect to the power inductor and output rectifier.</td>
</tr>
<tr>
<td>7</td>
<td>VDD</td>
<td>LDO Output</td>
</tr>
<tr>
<td>8, 9, 10, 11</td>
<td>PGND</td>
<td>Power Ground.</td>
</tr>
<tr>
<td>11</td>
<td>AGND</td>
<td>Analog Ground. Connect to the exposed pad at a single point.</td>
</tr>
<tr>
<td>12</td>
<td>SS</td>
<td>Soft-Start. Connect a soft-start capacitor to this pin. The soft-start capacitor charges from a 6μA constant current. Leave disconnected if the soft-start is not used.</td>
</tr>
<tr>
<td>13</td>
<td>FB</td>
<td>Feedback Input. Reference voltage is 1.25V. Connect a resistor divider to this pin.</td>
</tr>
<tr>
<td>14</td>
<td>FSET</td>
<td>Frequency Set. Connect a resistor from this pin to AGND. FSET pin voltage is internally regulated to 0.5V. The current flowing out of this pin linearly sets the operating frequency.</td>
</tr>
<tr>
<td>15</td>
<td>EP</td>
<td>Exposed Pad. The bottom exposed pad is the power ground. For best thermal dissipation, solder the exposed pad to the underlying cooper backplane.</td>
</tr>
</tbody>
</table>
BLOCK DIAGRAM

Figure 1: Functional Block Diagram
APPLICATION INFORMATION

Components referenced below apply to the Typical Application Circuits on both page 1 and Figure 4.

Theory of Operation

The MPQ3426 uses a constant-frequency, peak-current-mode, boost regulator architecture to regulate the feedback voltage. Refer to the functional block diagram for the MPQ3426’s operating principles.

At the beginning of each cycle, the N-Channel MOSFET switch turns on, causing the inductor current to rise. The current-sense amplifier (CSA) at the switch’s source internally converts the switch current to a voltage. This voltage goes to a comparator that compares it to the COMP voltage. The COMP voltage is the output of the error amplifier, which is an amplified version of the difference between the 1.225V reference voltage and $V_{FB}$.

When $V_{CSA}$ and $V_{COMP}$ are equal, the PWM comparator turns off the switch to force the inductor current through the external rectifier to the output capacitor. This decreases the inductor current. $V_{COMP}$ controls the peak inductor current, which is controlled by the output voltage. The output voltage is regulated by the inductor current to satisfy the load. Current-mode regulation improves the transient response and control-loop stability.

Selecting the Switching Frequency

The switching frequency is set by the FSET resistor ($R_{FSET}$), where:

$$ f_{FSET} = 23 \times (R_{FSET})^{-0.86} $$

Where $R_5$ is in kΩ

EN UVLO Hysteresis

The MPQ3426 features a programmable UVLO hysteresis. Upon power up a 4µA current sink ($I_{SINK}$) is applied to the EN pin, requiring a higher $V_{IN}$ to overcome the current sink. That extra voltage on $V_{IN}$ equals

$$(I_{SINK} + I_{R_{BOTTOM}}) \times R_{TOP}$$

Once the EN pin reaches about 1.5V (the EN turn-on threshold), the MPQ3426 starts and the current sink turns off to create the reverse hysteresis for $V_{IN}$ falling. This hysteresis is determined by:

$$ UVLO_{Hysteresis} = 4\mu A \times R_{TOP} $$

At the same time $V_{IN}$ startup threshold is determined by its UVLO or:

$$ V_{IN} = 1.5 \times \frac{R_{TOP} + R_{BOTTOM}}{R_{BOTTOM}} + UVLO_{Hysteresis} $$

Depending on whichever is big, $V_{IN}$ in unit V and $R_{TOP}/R_{BOTTOM}$ in MΩ.

![Figure 2: EN Resistor Divider](image)

Table 1: Switching Frequency vs. FSET Resistor Values

<table>
<thead>
<tr>
<th>$R_{FSET}$ (kΩ)</th>
<th>Freq (MHz)</th>
</tr>
</thead>
<tbody>
<tr>
<td>180</td>
<td>0.26</td>
</tr>
<tr>
<td>160</td>
<td>0.29</td>
</tr>
<tr>
<td>150</td>
<td>0.31</td>
</tr>
<tr>
<td>143</td>
<td>0.32</td>
</tr>
<tr>
<td>66.5</td>
<td>0.62</td>
</tr>
<tr>
<td>35.7</td>
<td>1.06</td>
</tr>
<tr>
<td>25</td>
<td>1.44</td>
</tr>
<tr>
<td>18</td>
<td>1.91</td>
</tr>
<tr>
<td>16</td>
<td>2.12</td>
</tr>
</tbody>
</table>

Selecting the Soft-Start Capacitor

The MPQ3426 includes a soft-start timer that limits the COMP voltage during startup to prevent excessive input current. This prevents premature source voltage termination at startup due to input-current overshoot. When power is applied to the MPQ3426, and EN goes HIGH, a 6µA internal current source charges the external SS capacitor. As the SS capacitor charges, the SS
Voltage rises. When the SS voltage reaches 250mV, the MPQ3426 starts switching at 1/5 the programmed frequency (frequency fold-back mode). At 800mV the switching frequency rises to the programmed value. The soft-start ends when the SS voltage reaches 2.5V. This limits the inductor current at start-up, forcing the input current to rise slowly to the required current to regulate the output voltage.

The soft-start period is determined by the equation:

$$t_{SS} = \frac{C_{SS} \times 10^{-9} \times 2.5V}{6\mu A}$$

Where $C_{SS}$ (nF) is the soft-start capacitor from SS to GND, and $t_{SS}$ is the soft-start period.

Setting the Output Voltage
$V_{OUT}$ connects to the top of a resistor divider (R2 and R3); the resistor divider’s tap connects to the FB pin. The feedback voltage is typically 1.225V. The output voltage is then:

$$V_{OUT} = V_{FB} \times \left(1 + \frac{R2}{R3}\right)$$

Where:
- R2 is the top feedback resistor
- R3 is the bottom feedback resistor
- $V_{FB}$ is the feedback reference voltage (typically 1.225V)

To increase efficiency, use $\geq 10k\Omega$ feedback resistors.

Selecting the Input Capacitor
The input requires a capacitor to supply the AC ripple current to the inductor, while limiting noise at the input source. Use a low-ESR capacitor with a value $>4.7\mu F$ to minimize the IC noise. Ceramic capacitors are preferred, but tantalum or low-ESR electrolytic capacitors can also suffice. However, since it absorbs the input switching current it requires an adequate ripple current rating. Use a capacitor with an RMS current rating greater than the inductor ripple current.

To ensure stable operation, place the input capacitor as close to the IC as possible. As an alternative, place a small, high-quality ceramic 0.1µF capacitor close to the IC and place the larger capacitor further away. If using the latter technique, use either tantalum- or electrolytic-type capacitors for the larger capacitor. Place all ceramic capacitors close to the MPQ3426.

Selecting the Output Capacitor
The output capacitor maintains the DC output voltage. For best results, use low-ESR capacitors to minimize the output voltage ripple. The output capacitor’s characteristics also affect regulatory control system’s stability. For best results, use ceramic, tantalum, or low-ESR electrolytic capacitors. For ceramic capacitors, the capacitance dominates the impedance at the switching frequency, and so the output voltage ripple is mostly independent of the ESR. The output voltage ripple is estimated as

$$V_{RIPPLE} \approx \frac{1 - \frac{V_{IN}}{V_{OUT}}}{C_{OUT} \times f_{SW}} \times I_{LOAD}$$

Where $V_{RIPPLE}$ is the output ripple voltage, $V_{IN}$ and $V_{OUT}$ are the DC input and output voltages, respectively, $I_{LOAD}$ is the load current, $f_{SW}$ is the switching frequency, and $C_{OUT}$ is the value of the output capacitor.

For tantalum or low-ESR electrolytic capacitors, the ESR dominates the impedance at the switching frequency, and so the output ripple is:

$$V_{RIPPLE} \approx \frac{1 - \frac{V_{IN}}{V_{OUT}}}{C_{OUT} \times f_{SW}} \times I_{LOAD} \times R_{ESR} \times \frac{V_{OUT}}{V_{IN}}$$

Where $R_{ESR}$ is the equivalent series resistance of the output capacitors.

Choose an output capacitor that satisfies the output ripple and load transient requirements of the design. A 4.7µF-to-22µF ceramic capacitor is suitable for most applications.

Selecting the Inductor
The inductor forces the output voltage higher than the input voltage. A larger inductor value results in less ripple current and reduces the peak inductor current; this reduces the stress on the internal N-channel switch. However, a larger inductor is physically larger, has a higher series resistance, and/or lower saturation current.
A good rule of thumb is to allow the peak-to-peak ripple current to equal 30% to 50% of the maximum input current. Make sure that the peak inductor current is less than 75% of the current limit during duty-cycle operation to prevent regulator losses due to the current limit. Also make sure that the inductor does not saturate under the worst-case load transient and startup conditions. Calculate the required inductance value using the following equations:

\[
L = \frac{V_{\text{IN}} \times (V_{\text{OUT}} - V_{\text{IN}}) \times f_{\text{SW}} \times \Delta I}{V_{\text{OUT}} \times I_{\text{LOAD(MAX)}} \times \eta}
\]

Where:
- \(I_{\text{LOAD(MAX)}}\) = maximum load current
- \(\Delta I\) = peak-to-peak inductor ripple current
- \(\eta\) = efficiency.

**Selecting the Diode**

The output rectifier diode supplies current to the inductor when the internal MOSFET is off. Use a Schottky diode to reduce losses due to the diode forward voltage and recovery time. The diode should be rated for a reverse voltage equal to or greater than the expected output voltage. The average current rating must exceed the maximum expected load current, and the peak current rating must exceed the peak inductor current.

**Compensation**

The output of the transconductance error amplifier (COMP) compensates the regulation control system. The system uses two poles and one zero to stabilize the control loop. The poles are \(f_{P1}\) (set by the output capacitor \(C_{\text{OUT}}\) and the load resistance) and \(f_{P2}\) (set by the compensation capacitor \(C_{\text{COMP}}\) and the compensation resistor \(R_{\text{COMP}}\)). These are determined by the equations:

\[
f_{P1} = \frac{1}{2 \times \pi \times R_{\text{LOAD}} \times C_{\text{OUT}}} \quad (\text{Hz})
\]

\[
f_{P2} = \frac{G_{\text{EA}}}{2 \times \pi \times A_{\text{VEA}} \times C_{\text{COMP}}} \quad (\text{Hz})
\]

Where \(R_{\text{LOAD}}\) is the load resistance, \(G_{\text{EA}}\) is the error amplifier transconductance, and \(A_{\text{VEA}}\) is the error amplifier voltage gain.

The DC loop gain is

\[
A_{\text{VDC}} = \frac{A_{\text{VEA}} \times V_{\text{IN}} \times R_{\text{LOAD}} \times V_{\text{FB}} \times G_{\text{CS}}}{0.5 \times V_{\text{OUT}}^2} \quad (\text{V/V})
\]

Where \(G_{\text{CS}}\) is the compensation voltage/inductor current gain, and the \(V_{\text{FB}}\) is the feedback regulation threshold.

There is also a right-half-plane zero \((f_{RHPZ})\) that exists in continuous conduction mode (the inductor current does not drop to zero for each cycle). The \(f_{RHPZ}\) is:

\[
f_{RHPZ} = \frac{R_{\text{LOAD}}}{2 \times \pi \times L} \times \left(\frac{V_{\text{IN}}}{V_{\text{OUT}}}\right)^2 \quad (\text{Hz})
\]

Table 2 lists a few compensation component combinations for different input voltages, output voltages and capacitances for the most-frequently-used output ceramic capacitors. Ceramic capacitors generally have extremely low ESR, and therefore do not require the second compensation capacitor (from COMP to GND).

For faster control loop and better transient response, select \(C_{\text{COMP}}\) (C7) from Table 2: Recommended Component Values. Then gradually increase the \(R_{\text{COMP}}\) (R6) value and check the load step response to find a value that minimizes any output voltage ringing or overshoot at the load step edge. Finally, check the compensator design by calculating the DC loop gain and the crossover frequency. The crossover frequency where the loop gain drops to 0dB (a gain of 1) can be obtained visually by placing a -20dB/decade slope at each pole, and a +20dB/decade slope at each zero. The crossover frequency should be at least one decade below the \(f_{RHPZ}\) at the maximum output load current to obtain a high-enough phase margin for stability.
Table 2: Recommended Component Values

<table>
<thead>
<tr>
<th>V_{IN} (V)</th>
<th>V_{OUT} (V)</th>
<th>C_{OUT} (µF)</th>
<th>R_{COMP} (kΩ)</th>
<th>C_{COMP} (nF)</th>
<th>Switching Frequency (kHz)</th>
<th>Inductor (µH)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.2</td>
<td>12</td>
<td>4.7</td>
<td>10</td>
<td>6.8</td>
<td>600</td>
<td>8.2</td>
</tr>
<tr>
<td>3.2</td>
<td>12</td>
<td>10</td>
<td>15</td>
<td>6.8</td>
<td>600</td>
<td>8.2</td>
</tr>
<tr>
<td>3.2</td>
<td>12</td>
<td>22</td>
<td>30</td>
<td>6.8</td>
<td>600</td>
<td>8.2</td>
</tr>
<tr>
<td>5</td>
<td>12</td>
<td>10</td>
<td>12</td>
<td>4.9</td>
<td>600</td>
<td>6.8</td>
</tr>
<tr>
<td>5</td>
<td>12</td>
<td>22</td>
<td>25</td>
<td>4.9</td>
<td>600</td>
<td>6.8</td>
</tr>
<tr>
<td>5</td>
<td>18</td>
<td>4.7</td>
<td>12</td>
<td>4.9</td>
<td>600</td>
<td>10</td>
</tr>
<tr>
<td>5</td>
<td>18</td>
<td>10</td>
<td>25</td>
<td>4.9</td>
<td>600</td>
<td>10</td>
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<tr>
<td>5</td>
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<td>22</td>
<td>50</td>
<td>4.9</td>
<td>600</td>
<td>10</td>
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<tr>
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<td>24</td>
<td>4.7</td>
<td>10</td>
<td>6.8</td>
<td>600</td>
<td>10</td>
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<td>10</td>
<td>20</td>
<td>6.8</td>
<td>600</td>
<td>10</td>
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<tr>
<td>12</td>
<td>24</td>
<td>22</td>
<td>40</td>
<td>6.8</td>
<td>600</td>
<td>10</td>
</tr>
</tbody>
</table>

Layout Considerations

High frequency switching regulators require very careful layout for stable operation and low noise. Place all components as close to the IC as possible. Keep the path between L1, D1, and C_{OUT} extremely short to minimize noise and ringing. Place C_{IN} close to the VIN pin to maximize decoupling. Keep all feedback components close to the FB pin to prevent noise injection on the FB pin trace. Tie the C_{IN} and C_{OUT} ground returns close to the GND pin. Figure 3 shows the recommended component placement for the MPQ3426.

Design example

Below is a design example following the application guidelines for the following specifications:

<table>
<thead>
<tr>
<th>V_{IN}</th>
<th>V_{OUT}</th>
<th>f_{SW}</th>
</tr>
</thead>
<tbody>
<tr>
<td>8V-22V</td>
<td>24V</td>
<td>300kHz</td>
</tr>
</tbody>
</table>

The typical application circuit for VOUT = 24V on page 1 shows the detailed application schematic, and is the basis for the typical performance and circuit waveforms. For more detailed device applications, please refer to the schematic on page 1.
TYPICAL APPLICATION CIRCUIT

Figure 4: Typical Application Schematic—15V Output
PACKAGE INFORMATION (FOR MPQ3426DLE)
QFN14 (3X4mm)

NOTE:
1) THE LEAD SIDE IS WETTABLE.
2) ALL DIMENSIONS ARE IN MILLIMETERS.
3) EXPOSED PADDLE SIZE DOES NOT INCLUDE MOLD FLASH.
4) LEAD COPLANARITY SHALL BE 0.08 MILLIMETERS MAX.
5) JEDEC REFERENCE IS MO-220.
6) DRAWING IS NOT TO SCALE.
PACKAGE INFORMATION (FOR MPQ3426DL)
QFN14 (3X4mm)

NOTE:
1) ALL DIMENSIONS ARE IN MILLIMETERS.
2) EXPOSED PADDLE SIZE DOES NOT INCLUDE MOLD FLASH.
3) LEAD COPLANARITY SHALL BE 0.10 MILLIMETER MAX.
4) DRAWING CONFORMS TO JEDEC MO-229, VARIATION VEED-5.
5) DRAWING IS NOT TO SCALE.

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